Table of Contents

Thursday, December 8, 2011

TA1-1: Interfaces for Teleoperations

TA1-2: Medical Robotics I

TA1-3: Walking Robots I

TA1-7: Biomimetic Control

TA2-1: Control of Teleoperations

TA2-2: Medical Robotics II

TA2-3: Walking Robots II

TA2-4: Vision for Robot Navigation

TA2-5: Sensing for Detection and Localization II

TA2-6: Motion Planning and Control for Mobile Robots I

TP-P: Poster Session I: Robotics

TP2-1: Multiple and Swarm Robots

TP2-2: Medical Robotics IV

TP2-3: Robotic Systems

TP2-4: 3D Image Analysis

TP2-5: Sensing for Detection and Localization IV

TP2-6: Motion Planning and Control for Mobile Robots III

FA1-6: Control of Flexible Robots

FA1-7: Flying Robots I

FA2-1: Grasping and Manipulation II

FA2-2: Assist and Rehabilitation Robotics I

FA2-3: Mobile Robots III

FA2-4: Micro/Nano Actuation and Manipulation

FA2-5: Tactile Sensing

FA2-6: Control of Mobile and Aerial Robots

FA2-7: Flying Robots II

FP1-1: Grasping and Manipulation III

FP1-2: Assist and Rehabilitation Robotics II

FP1-3: Mobile Robots IV

FP1-4: Vision for Robot Control I

FP1-5: Human Detection

FP1-6: Underwater Robots I

FP1-7: Service Robots

FP-P: Poster Session II: Biomimetics

FP2-1: Grasping and Manipulation IV

FP2-2: Assist and Rehabilitation Robotics III

FP2-3: Mobile Robots V

FP2-4: Vision for Robot Control II

FP2-5: Sensor Network

FP2-6: Underwater Robots II

FP2-7: Recent Results Session I

Saturday, December 10, 2011

SA1-1: Robot Design and Control

SA1-2: Assist and Rehabilitation Robotics IV

SA1-3: Humanoid Robots I

SA1-4: Video Session I: Biomimetics

SA1-5: Motion Measurement and Estimation

SA1-6: Hardware and Software Architecture for Robots

SA1-7: Recent Results Session II

SA2-1: Motion Control of Robots

SA2-2: Robot Force Control

SA2-3: Humanoid Robots II

SA2-4: Video Session II: Robotics

SP1-2: Novel Actuators I

SP1-3: Mobile Robots I

SP1-4: Mapping

SP1-5: Human-Robot Interaction I

SP1-6: Intelligent Control of Robots

SP2-1: Modular and Multi-Agent Systems

SP2-2: Novel Actuators II

SP2-3: Mobile Robots II

SP2-4: Vision for Object Tracking

SP2-5: Human-Robot Interaction II

SP2-6: Control for Human-Robot Interaction